FORMAL REQUIREMENTS FOR MICROGRID USING KAOS AND REFERENCE ARCHITECTURE

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Abstract— This paper presents a method for specifying requirements, applied to the operation of a microgrid. The challenge is to model Smart Grid systems requirements using formal methods based on schematic representations that will allow analysis, verification and validation, improving the reliability and performance of the design cycle. Considering the inherent complexity of these systems - generally heterogeneous, open and distributed - formal modeling is a key issue for the design of automated electrical systems to fit user experience expectations. In this article we propose a systemic approach that combines consolidated reference architectures and modern goal-oriented requirements engineering methods in the early steps of microgrid design. The formalism proposed is intended to obtain formal requirements models associated with standards and reference models proposed and accepted by the scientific and practitioner community.

Keywords— Requirements Engineering, KAOS, IEC 61850, Microgrid.

Resumo— Este artigo apresenta um método para especificação de requisitos, aplicado à operação de microgrids. O desafio é modelar os requisitos de sistemas Smart Grid usando métodos formais baseados em linguagens esquemáticas que dêem suporte ao processo de análise, verificação e validação de modo a melhorar a confiabilidade e desempenho do ciclo de projeto. Considerando a complexidade inerente desses sistemas - geralmente heterogêneos, abertos e distribuídos - os métodos formais assumem um papel muito importante para o projeto de Sistemas Elétricos Automatizados que precisam interagir harmonicamente com os usuários. Neste artigo é proposta uma abordagem sistemática que combina arquiteturas de referência consolidadas e métodos engenharia de requisitos orientada a objetivos na fase inicial de projeto. O formalismo proposto busca sintetizar modelos formais de requisitos associados com padrões e modelos de referência aceitos pela comunidade acadêmica e pelos profissionais de mercado.

Palavras-chave— Engenharia de requisitos, KAOS, IEC61850, Microgrid.

1 Introduction

Electricity is a key element to improve the quality of life of the population. However, according to the Brazilian Institute of Geography and Statistics, about 729 thousand Brazilian families have no access to any energy resources, mainly because they live too far from the available resources and distributed network.

The implementation of Smart Grid (SG) systems with renewable energy generation has proven to be a viable alternative to diversify and rationalize energy supply needs, especially if it is based on the integration of different renewable sources.

In addition, SG systems have inherent complexity because they are eminently heterogeneous, open and distributed systems, demanded in different situations and application environments. Therefore, it implies knowledge domains that combine general and local information, making the design process quite complicated.

In this context, the life-cycle of the SG systems has an important initial phase, characterized by incomplete knowledge in the requirements

specification. On the other hand, in the early requirements phase it is strategically easier to deal with difficulties and physically easier to introduce changes. That turns the requirements phase significantly important to the success of the whole design, and must be treated as a necessary condition to the a good design performance.

In fact, the introduction of a structured requirements phase that anticipates formalization in the life-cycle of SG systems is a recent trend in electrical systems and has attracted the attention of researchers and implementers. Some existing methods consider a requirements phase in the life-cycle, but do not fully meet the requirements phase, they only satisfy some preliminary steps informally (Silva and Silva, 2015).

Several researches related to the design of energy systems have recently been carried out in the academy, searching for new, more robust, consistent and flexible methods, as shown in the literature:

In this context, some models and reference architectures have recently been proposed, such as IntelliGrid, an architecture proposed by the

Electric Power Research Institute (EPRI, USA) (Commission et al., 2008) or the SGAM architecture (Uslar et al., 2012). Both architectures recognize the importance of the requirements phase, which includes requirement elicitation, based on IEC / PAS 62559 and modeling, using (UML) Unified Modeling Language. A repository of Design Cases of requirements for Smart Grid systems was built, including features to transmission, distribution and integration.

Although there are other design methods for systems in general or specifically for SG, it turns out that the initial stage usually does not receive the attention it deserves. Requirements specification and analysis lack specific treatment methods and, consequently, result in difficulties and unnecessary costs in the rest of the life cycle (Mazzolini et al., 2011).

In addition, working with informal requirements seems to facilitate the design process but can lead to undetected failures during requirements specification (where error costs are lower) and compromises the project as a whole.

The complexity involved in dealing with a distributed arrangement of subsystems (not all done at the same time) is another important factor in justifying the use of formally closed and consistent methods that can be analyzed and verified before implementation.

In this paper we present a proposal for a formal modeling of microgrid systems requirements specification. The proposal is based on systems of systems approach that anticipates formalization through a schematic representation, associated to the Model Driven Engineering (MDE) scope, (Cretu and Dumitriu, 2014).

2 Conceptual description of the Method

A conceptual description of the method is depicted in Figure 1.

Figure 1: Method flowchart

Initially, a scenario is defined where the method will be applied, consisting of operational, geographic characteristics, environmental restrictions and local details that should be verified. In this step a reference architecture is selected to guide the process. For the proposed method we choose the IEC 61850.

Next, requirements are specified based on the chosen reference architecture. Therefore, the operation of the microgrid will follow the recommendations of the standard IEC 61850. Here, it is necessary to delimit the application domain, and development scope, that is, define the systems of

interest, inputs and outputs, interface and forms of communication. In fact, this is one of the most complicated steps, since important information may not be available.

In the next step, it is made the modeling of system requirements based on objectives, operations and agents responsible for meeting the objectives. The GORE (Goal Orientated Requirement Engineering) method is used, specifically the KAOS tool (Knowledge Engineering Object System). The use of this method introduces a more direct approach, collapsing aspects of functional and non-functional requirements. Following, the formal requirements specification is generated, both by KAOS diagrams and to a formal representation based on Linear Tree Logic (LTL).

The final step is the validation with stakeholders, through the analysis of LTL properties to check process properties like Security and Liveness, associated to the control solution for the microgrid, considering also its constraints.

3 Proposed Approach

The proposed method combines a new approach of the Objective-based Requirements Engineering (ER) with the reference model approach frequently used in energy system design, applied to the operation of a microgrid considering its technical peculiarities.

3.0.1 Microgrid System

Technically speaking, a microgrid is a low voltage distribution network, located downstream of a distribution substation through a Common Coupling Point (PCC). The microgrid consists of a set of components, including Intelligent Electronic Devices (IEDs), for sensing and control, as well as charging and monitoring tools for energy quality, a Control system that allows rapid diagnosis and accurate solutions for interruptions in the network or disconnections.

Figure 2: Proposed scenario for the microgrid

Therefore, a microgrid is a multi-source sys-

tem consisting of conventional Renewable Energy Sources (RES), storage systems and controllable loads. The interface between the service network and the microgrid is used to interact with the SG; it provides voltage control, power balancing, load sharing. A communications infrastructure, using communication networks that propitiated the transfer and exchange of data, in real time, Figure 2.

Therefore, microgrids play a key role in the integration of Distributed Generators (DG) and, in particular, RES (Sechilariu and Locment, 2016). However, the intermittent and unpredictable nature of the power supply continues to be a problem for integration with the service network, resulting in voltage and / or frequency fluctuations, harmonic pollution, and difficulty in charge management , etc.

In Brazil, there is great potential for the development of technologies for sustainable generation based on wind, solar, biomass and hydroelectric energy, among others. The integration of these technologies has become a priority in microgrids, not only for presenting DERs, but also for the need to integrate IED devices, sensing and measurement systems, network nodes with computing capacities, actuation systems with configuration and adjustment capability that allows integration with new devices.

3.0.2 Architecture IEC-61850

The IEC 61850 architecture was developed with the aim of being a communications architecture, that facilitated the design of electric systems of power for protection, control, monitoring and diagnostics functions in substations (Naumann et al., 2014).

Figure 3: Architecture Microgrid based IEC 61850

The architecture is not only deal communication, but also about the modeling of information tailored to the needs of the electric power industry (Berger and Iniewski, 2012), Figure 3.

Although the IEC 61850 originally addressed only substation automation, however, there are already additional information models defined

based on the IEC 61850 architecture for other domains such as renewable energy (Berger and Iniewski, 2012). In 2010, the US National Institute of Standards and Technology (NIST) recognized IEC 61850 as a major facilitator of the implementation of SG systems.

One of the main goals of this IEC 61850 architecture was to solve interface problems and standardize communication to avoid the use of manufacturer-specific protocols. Also, provides a mechanism for future automation and control functions that will allow electrical systems to evolve into SG (Naumann et al., 2014).

Currently, there are extensions and additional information models for microgrids domains, so IEC 61850-7-420 provides the information model and logical node (LNs) for DERs at the process level, including (ECPs) power converters, controllers, generators, power converters, DC converters, and auxiliary systems (such as as measuring devices). IEC 61850 7-1, 7-2, 7-3 and 7-4 provide the principle of modeling equipment information. IEC 61850 also provides object-oriented models for inverters, power storage systems, and others (Hongwei, 2014).

3.0.3 GORE:Goal Oriented Requirements Methods

Goal-orientation, is a recent ER approach used to capture requirements. GORE refers to the use of objectives for defining requirements, eliminating the traditional dichotomy between functional and non-functional requirements. The former is more intuitive and generally associated with services to be provided to customers while the latter is related to quality, sometimes performance or resources required for service, and also related to external demands such as safety requirements, performance, safety, aspects, etc. Here, a requirement is a necessary condition to reach a given goal in a specific application domain (Horkoff et al., 2017).

Therefore, since in the direct approach non-functional requirements are usually neglected or fail to compose a complete set, goal-oriented methods are becoming an interesting alternative to large systems. (Dardenne et al., 1993).

3.0.4 KAOS Graphic Representation

KAOS, is an ER method that covers the identification of requirements in the form of objectives whose graphical part is represented by diagrams, in order to build a formalizable model for the requirements. It is designed to adjust descriptions, analyze problems, clarify responsibilities, and allow stakeholders to communicate.

Requirements analysis with KAOS provides traceability, completeness, and unambiguity. On the other hands, the KAOS requirements model

consists of four submodels: objectives, objects, agents, and operations.

The goal model, represented by a graph or tree in which the main objective is (the root), where to the abstraction of the problem, can be refined into sub-objectives and refined until modeling requirements or expectations (tree leaves), which are the most basic objectives in the diagram hierarchy, and always associated with the agents.

If the agent is part of the system to be developed, it is a requirement, whereas the objective is an expectation if it is linked to an agent of the context.

3.0.5 Formal Representation (LTL)

An objective can be described as a valid final state, derived from the general behavior of the system. Separately, each sub-goal can emerge from different courses of action, but converge to the primary goal. Such behaviors can be represented as paths in a graph or as a combination of different automata.

The formal representation prescribed by the KAOS method is based on LTL, but can also be represented by a formal state transition representation. A transition can be represented formally in terms of LTL sentences, such as:

$$C \Rightarrow \Theta T$$

where C is a current condition, T is a target condition and is one of the LTL operators represented in Table 1.

Table 1: Temporal Logic Operators

Operator	Description
$\bigcirc$	In the next state
$\diamond$	Eventually in the future
$\square$	Always in the future
$\mathcal{U}d \leq$	Hold until is true

ER tools, such as ObjectivER, can help formalize the requirements specifications that come from the KAOS diagrams in LTL formulas. However, these formulas specify each process and it is not so easy to express distributed dynamics. In order to confront, several papers propose the translation of LTL representation for Petri nets (Silva and Silva, 2015).

4 Application of method

In this section, the proposed method for the operation of a microgrid, based on GORE and the reference model IEC 61850 is described. Initially, are extracted the minimum requirements for the operation of the microgrid based on the IEC 61850

reference model. Thus, Figure 4 shows the dynamics of the operation, also the control strategy is verified on each RSD, like all combinations.

Figure 4: Operation Microgrid based IEC 61850

Therefore, based on the context of the standard the DERs were grouped into programmable DER (DER-P) and non-programmable DER (DER-NP) (Postigo, 2018). The battery energy storage system (BESS) and Combined head and power (CHP) are part of the DER-P. On the other hand, renewable energy sources such as PV and WP belong to the DER-NPs, this is due to their uncertainty of power generation, and randomized in the production of energy, affected by natural factors. The Control system will be responsible for the automation and switching of the DERs.

Each DER accesses the microgrid bus through a circuit breaker. The microgrid connects to the service network by a PCC. When the turn off the PCC, closes the microgrid it accesses the electrical network and switches to the Connected Network Mode. When the switch it is open, the microgrid is disconnected from the service network and switches to Autonomous mode.

Autonomous Mode: It happens when the microgrid supplies power to the load only with the GD, that is, every time have some abnormal situation in the main network or happen a manual operation.

Synchronization mode: Whenever network power is reestablished, additional transition modes are required to synchronize distributed generation (DG) with the main network.

Network Mode Connected: Normal operation occurs when the microgrid is connected to the main network and distributed energies (DER).

Fault Mode: Whenever a fault is detected, the PCC switch opens, and MSG is separated from the service network and switches to autonomous mode.

The next step in the method is to model the requirements in the form of objectives using the objectives diagram. Figure 5, shows the KAOS model using the ObjectivER tool. It is observed how the main objective is refined in sub-targets, that is, the target Control of Operation of the microgrid, is refined in the submit Automatic Operation and Grid Operation connected. Also in

Figure 5: Goal Model

this model, each subroutine is refined into requirements and obstacles considered relevant to the field of microgrid operation, they are used to prove that the refinements are complete.

Figure 6: Object Model

Figure 6, shows the KAOS object model, which is an equivalent diagram with the UML class diagrams. They have characteristics such as inheritance and, is available for all types of objects (including associations).

In this diagram the objects (Available and Signal Type) are qualified with attributes, which captures the relevant vocabulary to express the objectives for microgrid control.

Figure 7, shows the operations diagram that represents all the behaviors agents need to have to meet their requirements. Thus the behaviors are expressed in terms of operations performed by the Controlling agent.

Figure 7: Operation Model

Figure 8: Responsibilities Model

Operations work on objects described in the object model (Available), which will allow objects to be created, object state transitions, or trigger other operations through events and signals sent and received by the IEDs.

Figure 8, shows the responsibilities diagram, which describes the responsibilities for each agent, the requirements and expectations for which they are responsible or that have been assigned to the Controlling agents and IEDs. Here, we check the different requirements and expectations in the objectives model and assign an agent to each of them.

The final step of the process is the formalization of requirements where KAOS is also used. Therefore, the process described so far is based on the hypothesis that the requirements must be formalized before they become specifications. Thus, the requirements are introduced as disciplined semi-formal declarations (since we are using reference models) and must be formally analyzed, using the LTL of the KAOS tool. This process is very important for the automation system that interacts with the SG system.

Table 2 shows LTL sentences associated with each goal.

5 Conclusion

This work is based on the hypothesis that in order to achieve good performance, SG systems must be automated and therefore their design should

Table 2: LTL sentences associated to each goal of Goal Model

Goal	LTL Sentences
A “Control Operation” of SG was done successfully.	$\forall(pcc:PCC, grid:Grid);$ $on(pcc) \rightarrow \Diamond grid.mode = true;$
Operation on “Autonomous Mode” was enabled.	$\exists(pcc:PCC, grid:Grid);$ $Of(pcc) \rightarrow \Diamond autonomousMode(grid);$
Operation on “Grid-connected mode” was enabled.	$\exists(op:Operator, grid:Grid);$ $On(grid) \wedge Available(op) \rightarrow$ $\Diamond manualOperation(op, grid);$
A “Commutation” was enabled.	$\exists(sinal:Sinal, com:Commutation);$ $\neg enabled(com) \wedge \neg disturbance(sinal)$ $\rightarrow \Diamond enabled(com) \wedge supply(sinal);$
A “Synchronization” was enabled.	$\exists(sinal:Sinal);$ $\neg disturbance(sinal) \wedge supply(sinal) \rightarrow$ $\Diamond synchronized(sinal);$
A “Fault operation” was detected.	$\exists(sinal:Sinal, pcc:PCC);$ $\neg disturbance(sinal) \wedge \neg supply(sinal)$ $\rightarrow \Diamond of(pcc);$
Detected “Disturbance” on Grid.	$\exists(ide-1:IDE-1, sinal:Sinal);$ $On(ide-1) \rightarrow \Diamond disturbance(sinal);$
Available “Utility Grid Supply”.	$\exists(ide-2:IDE-2, sinal:Sinal);$ $On(ide-2) \rightarrow \Diamond supply(sinal);$

no longer be based on good practices and experience based on intuitive and / or tacit knowledge. Automation can also introduce autonomy into the control systems, which could be a source of problems rather than advantages, if not well managed.

Thus, the proposal presented here combines consolidated reference architectures with modern objective-oriented requirements modeling, specification and analysis methods, aiming to provide reliable microgrid design, capable of managing from simple urban problems until sophisticated cases in remote locations.

In addition, using GORE, KAOS and reference model, the proposal introduces LTL-based (formal) requirements analysis and validation. However, it is observed there are not significant numbers of cases with this method developed to support direct comparison with traditional methods such as UML. Although, the case study presented in this paper clearly shows the advantage and reliability of the GORE approach.

The drawback of the proposal is associated with the formal presentation in LTL, which is not appropriated to distributed systems. Future steps of this research will investigate the use of Petri nets to provide a dynamical modeling and

formal verification in these systems.

Finally, this work shows a method for formal specification of requirements that allows the synthesis of control and operating modes for a microgrid based on the IEC 61850 architecture. The use of GORE methodology eliminates problems with the equilibrium between functional and non functional requirements that are present in the conventional approach based on UML, besides being traceable and easy to reuse.

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